

Welcome to Eclipse OpenMCx

EclipseCon 2021, Community Day - 25.10.2021

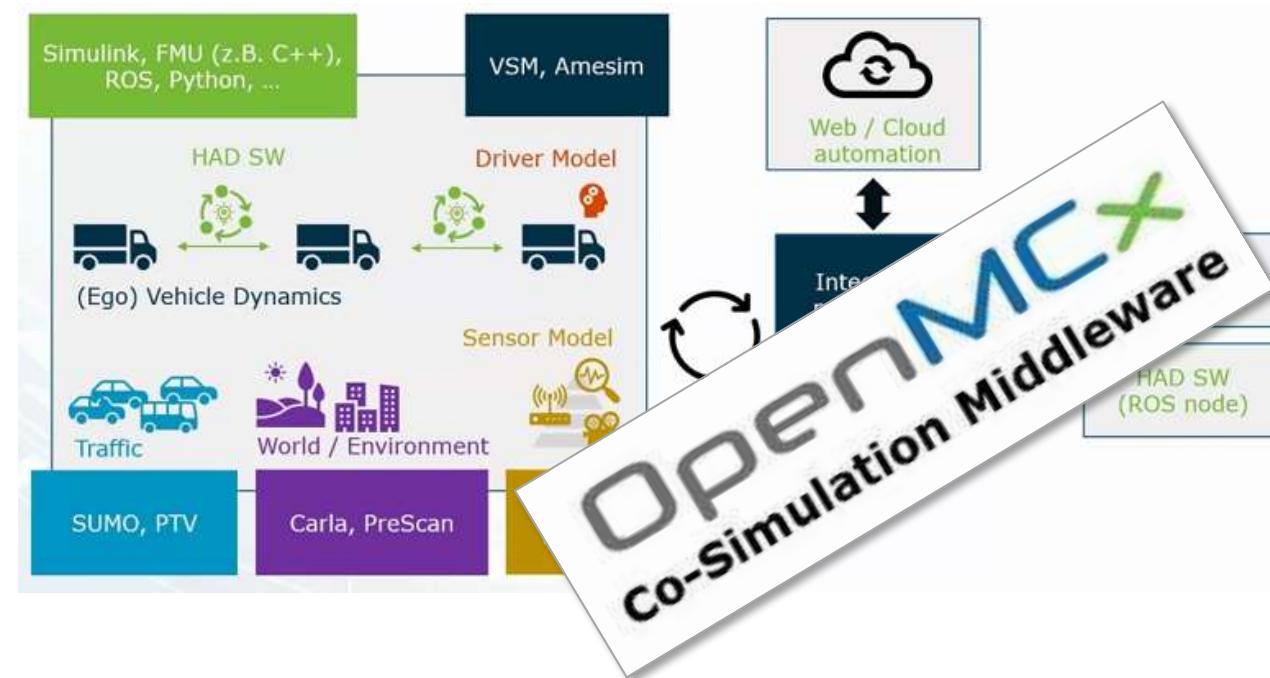
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Agenda

- Intro J. Balic (2+ min)
- OpenMCx K. Schuch (8+ min)
- Demo S. Terres (10+ min)
- Q&A All (10- min)

At **AVL** we believe that:...

- A. **ADAS/AD virtual validation** is one of the hottest topics out there (automotive-SW-wise😊)
- B. Setting up a virtual system is a **complex task** (environment, sensors, controls, vehicle, analytics,...)
- C. Validation efficiency can be increased by a standard-based **open co-simulation** middleware (mix-and-match)
- D. **There is no one-size-fits-all** toolchain (use-case specific: perception and fusion, planning and controls, system validation, driver experience, security and safety,...)
- E. The add-ons to the middleware should be **application driven** (democratize plug-ins development: environment, HiL, cloud, sensor integration,...)



Intro

01/2018



06/2019



09/2021

The OpenADx Working Group wants to serve in the field of **software tools for** the realization of **autonomous driving** by defining **open interfacing standards** for software for use **in-vehicle based systems and in testing environments**, under the governance of the **Eclipse Foundation**.

"**Eclipse OpenMCx**" is an open, tool-neutral **co-simulation middleware** based upon simulation standards and formats, such as **FMI, SSP, DCP, OSc, OSI, etc.** aiming to support **advanced simulation applications** with a heterogenous toolchain in a distributed **collaborative development process**.

<https://github.com/eclipse/openmcx>

<https://projects.eclipse.org/proposals/eclipse-openmcx>

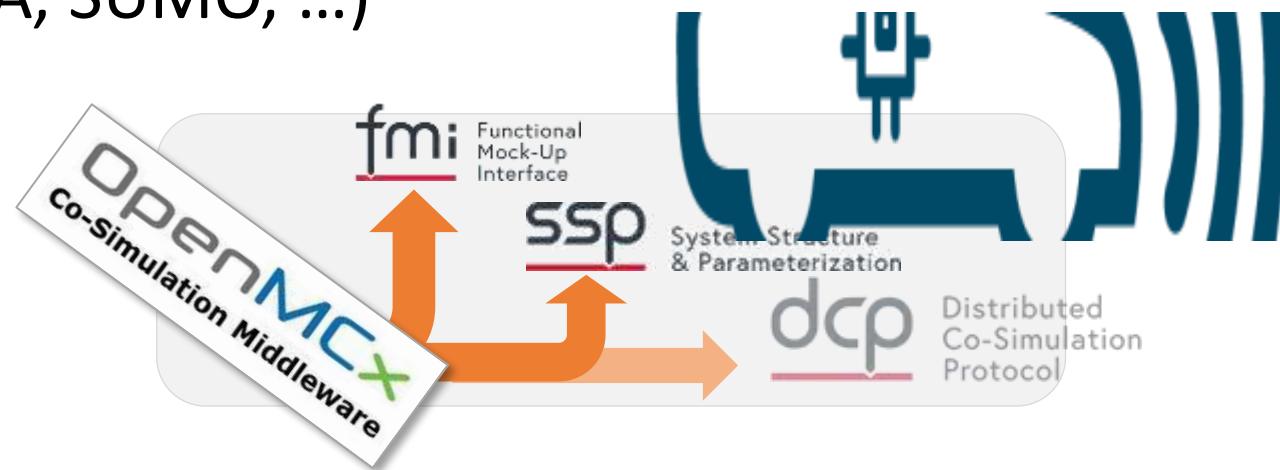
Our goal:

- Providing a referent implementation for promoting standards-based co-simulation methodology and enable the end-users to concentrate on their innovation process using use-case specific, best-in-class models and tool-chains.
- Making the world a better place! At least a bit.😊

OpenMCx

Co-Simulation Middleware

- Co-simulation Framework based on ([Modelica Association](#)) standards: FMI, SSP, DCP, etc.
- Open for interfacing with other (quasi) standards and tools (python, OSI, ROS2, CARLA, SUMO, ...)



OpenMCx

Co-Simulation Middleware

- System Structure Definition (*.ssd) input file (www.ssp-standard.org)
 - annotations for run-time config (default values if undefined)
- Features:
 - Parallel (Multi-Threading) or sequential execution
 - Unit-conversion
 - Parameter support
 - Result writing
 - binary port support (FMI2.0 with [OSI Sensor Model Packaging](#))
 - ...
- How to use (build, run, debug) OpenMCx?

<https://github.com/eclipse/openmcx>

LIVE SET-UP DEMO.

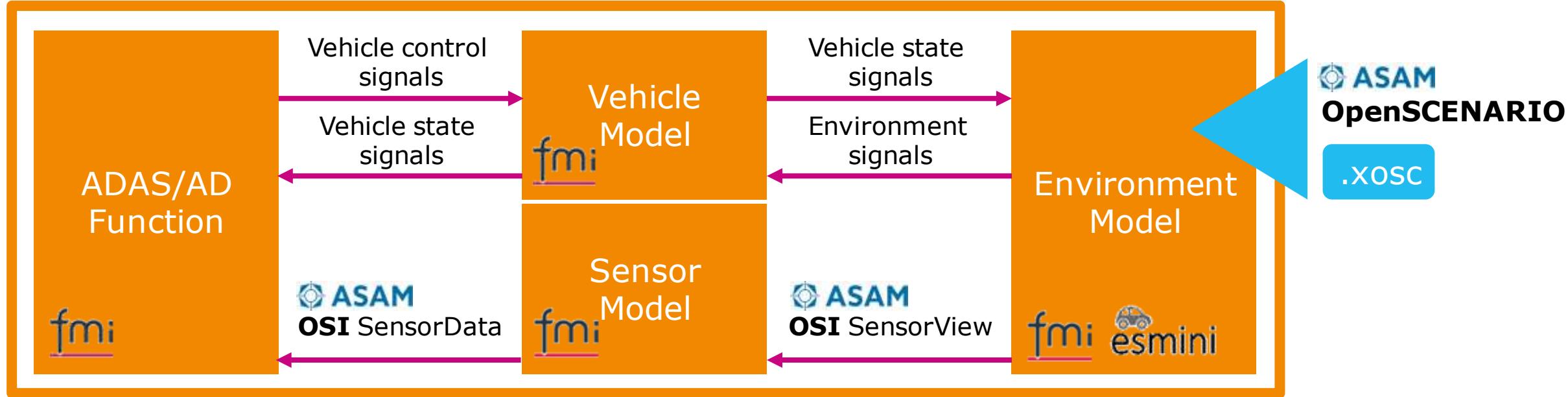
Klaus Schuch

Scenario-based testing of cyber-physical systems

powered by **OpenMCx**



System Structure Definition (SSD)



Simulation

OpenMCx
Co-Simulation Middleware



Results

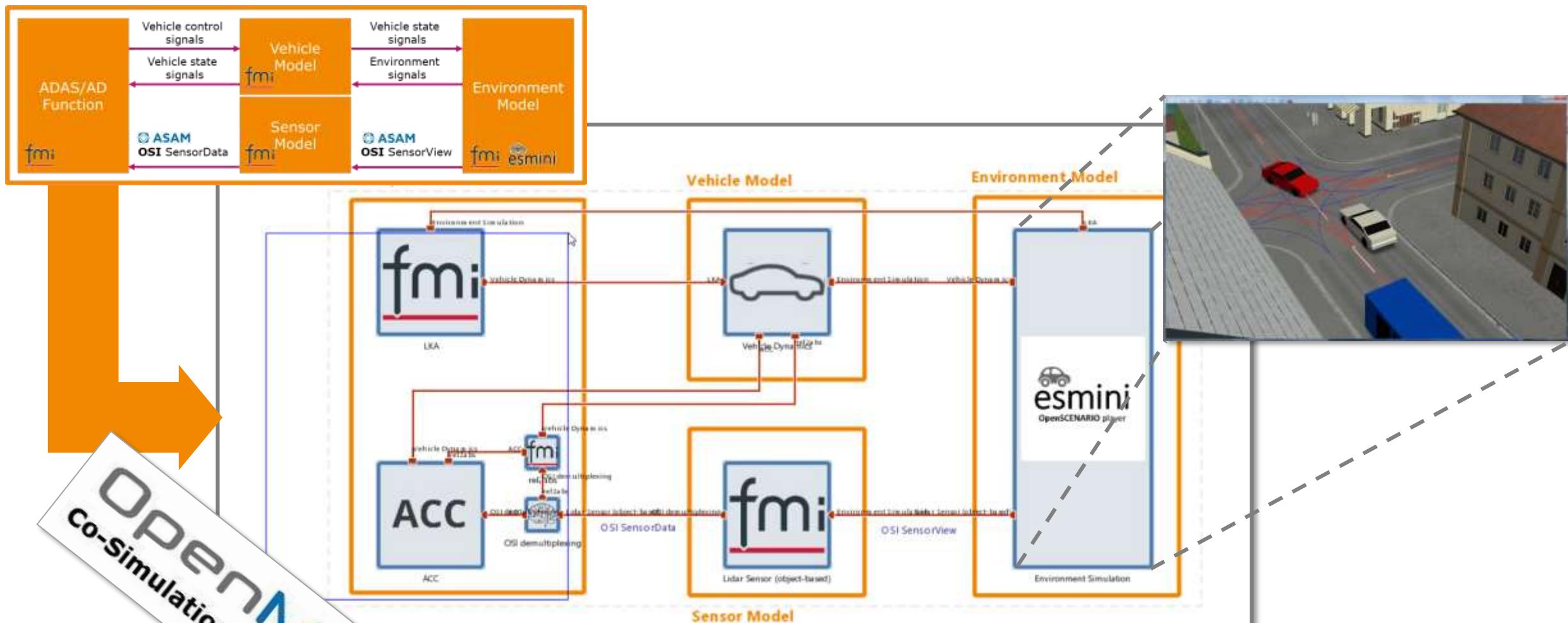
.csv
OSI trace



Analysis

Calculate KPIs

- Time to collision
- Perceived safety
- ...



LIVE SIMULATION DEMO.

Simon Terres

<https://github.com/eclipse/openmcx>

Thank you



www.avl.com

Contact us:

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Come and contribute!

<https://github.com/eclipse/openmcx>